



Petroleum and Mining Department  
Second Grade- Fall Semester

*Statics- 3D of force (Lecture 3)*

Lecturer: Ms. Jwan Khaleel M.



## **Lecture Content:**

- Cartesian Vectors
- Addition of Cartesian Vectors
- Position Vectors
- Force Vector Directed Along a Line
- Dot Product
- Solving problems

## **Learning Outcomes:**

**At the end of this lecture, you will be able to:**

- Evaluate the system of force methods for three-dimensional system.
- Express the position vector and how to use it.
- Introduce the dot product in order to determine the angle between two vectors or the projection of one vector onto another.
- Solving problems using related equations

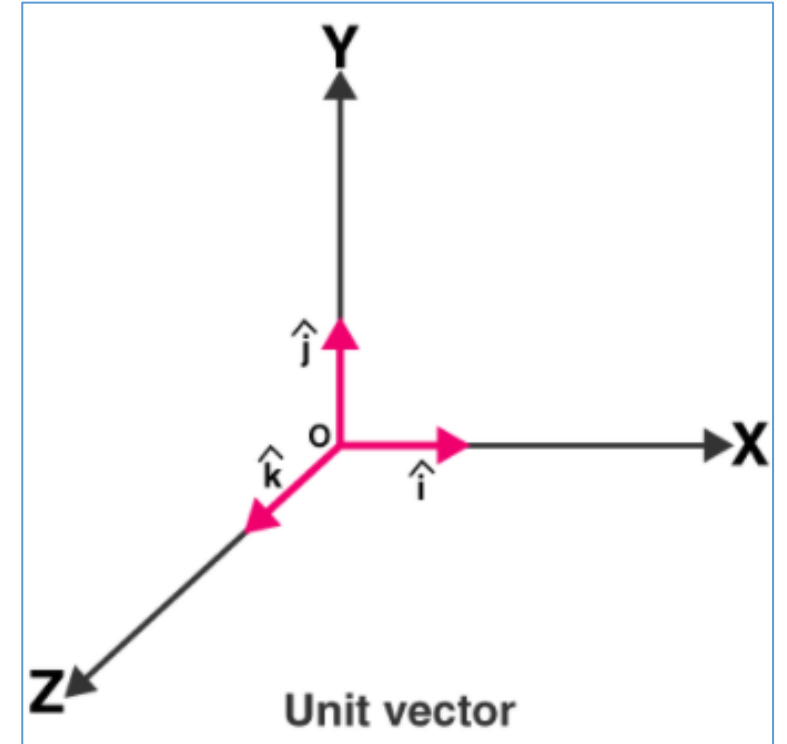
# Unit Vector:

A vector is a quantity that has both magnitude, as well as direction. A vector that has a magnitude of **1** is a unit vector. It is also known as Direction Vector.

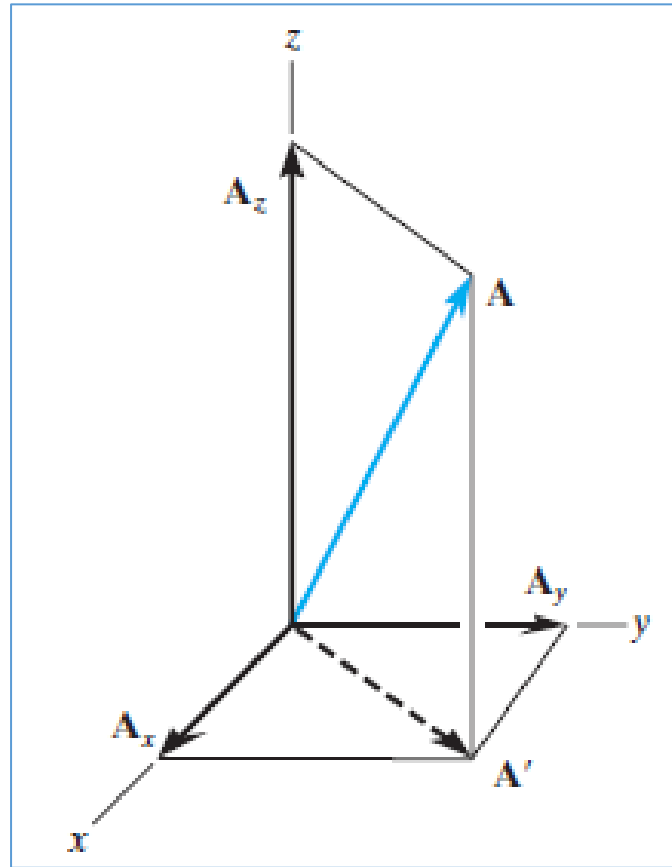
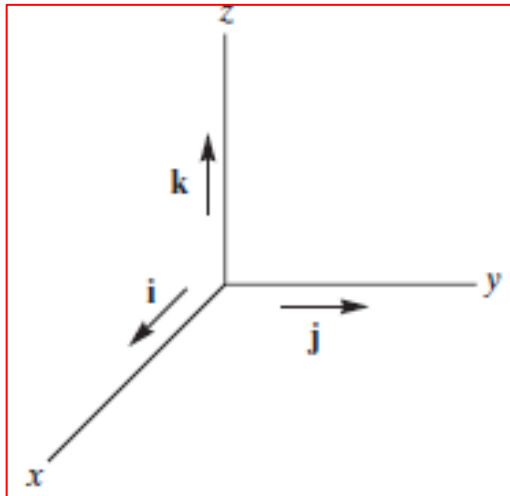
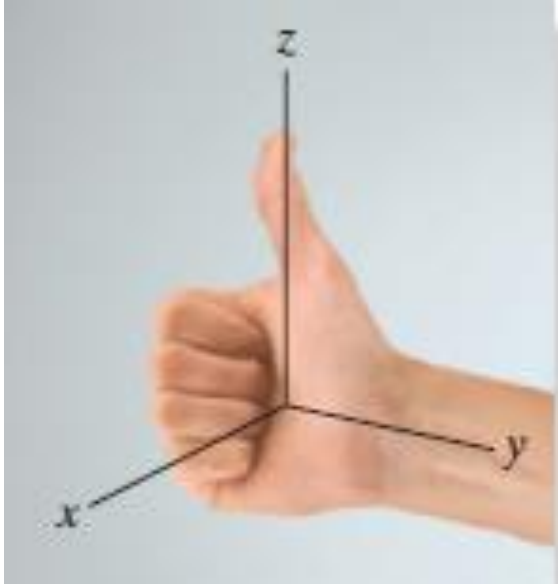
$$\text{Unit Vector} = \frac{\text{Vector}}{\text{Magnitude of Vector}}$$

**EXAMPLE//** Find the unit vector  $\vec{q}$  for the given vector,  $-2\hat{i}+4\hat{j}-4\hat{k}$ . Show Unit vector component  $\mathbf{q}$ .

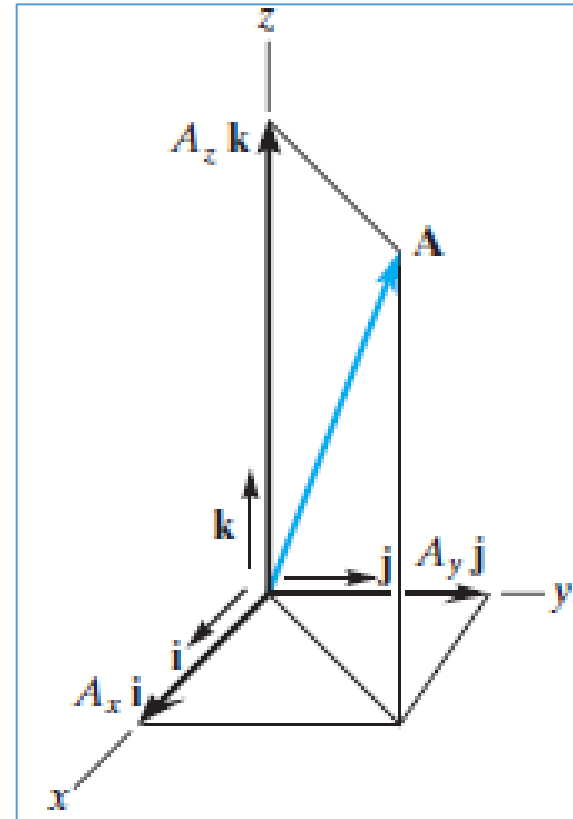
$$\mathbf{q} = \frac{-2\hat{i}+4\hat{j}-4\hat{k}}{\sqrt{(-2)^2+(4)^2+(-4)^2}} = \frac{-2\hat{i}+4\hat{j}-4\hat{k}}{\sqrt{36}} = \frac{-2\hat{i}+4\hat{j}-4\hat{k}}{6} = \frac{-2\hat{i}}{6} + \frac{4\hat{j}}{6} - \frac{4\hat{k}}{6} = \frac{-1}{3}\hat{i} + \frac{2}{3}\hat{j} - \frac{2}{3}\hat{k}$$



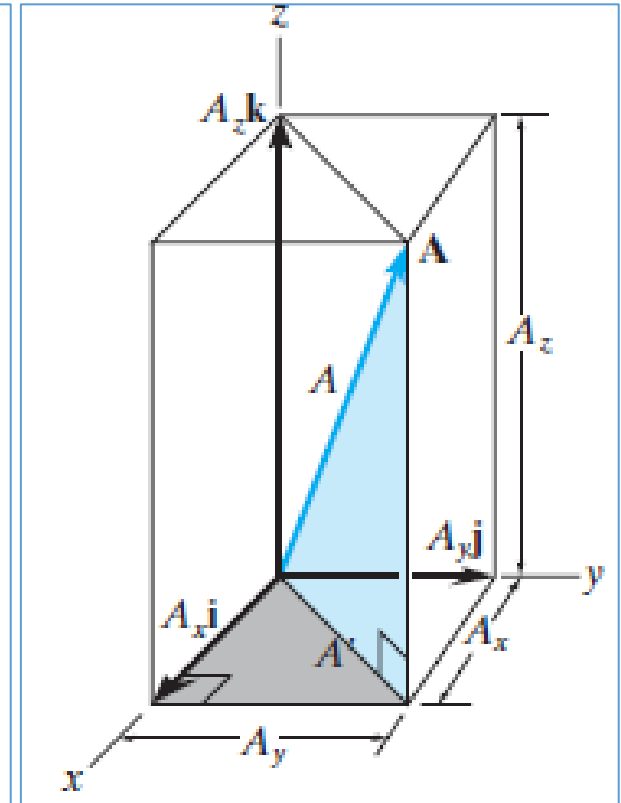
- *Cartesian Vectors:*



$$\mathbf{A} = A_x \mathbf{i} + A_y \mathbf{j} + A_z \mathbf{k}$$

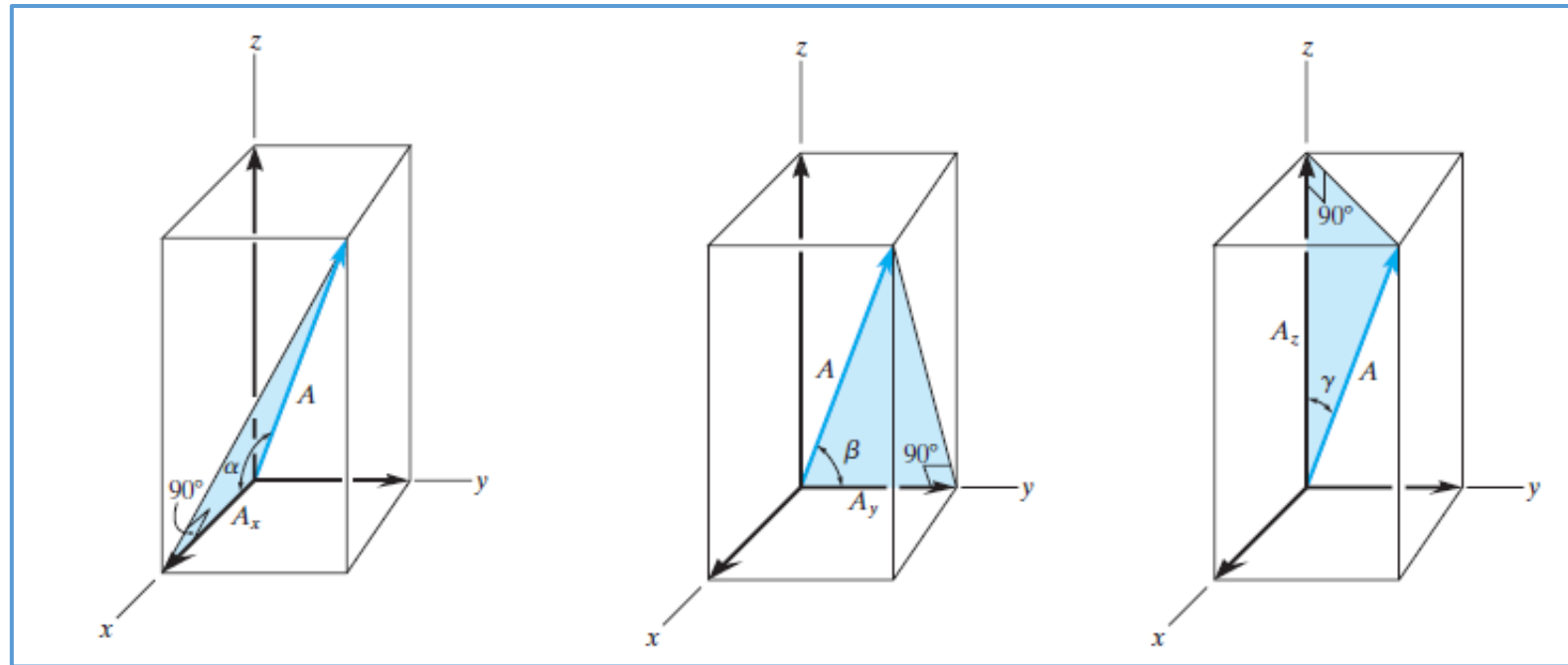
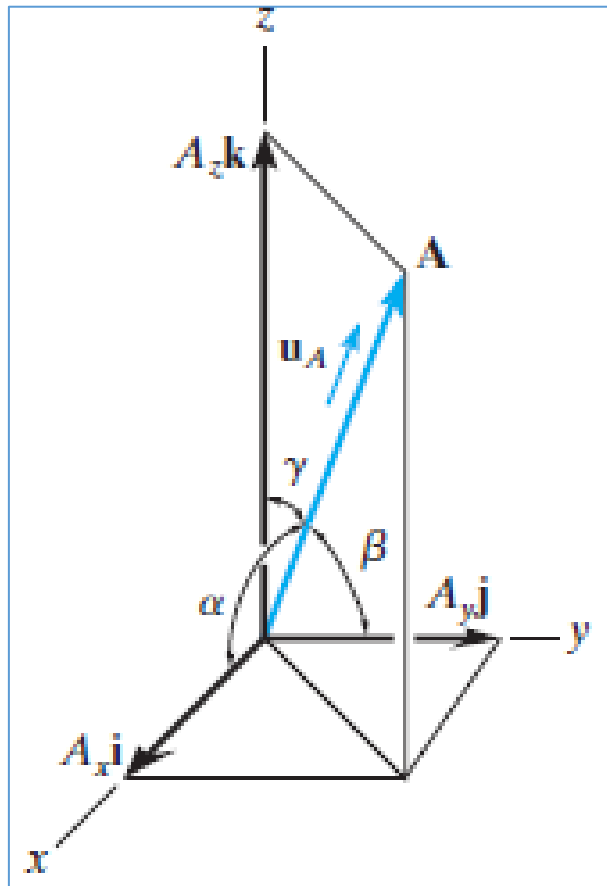


$$\mathbf{A} = A_x \mathbf{i} + A_y \mathbf{j} + A_z \mathbf{k}$$



$$A = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

# • Cartesian Vectors:



$$\cos \alpha = \frac{A_x}{A}$$

$$\cos \beta = \frac{A_y}{A}$$

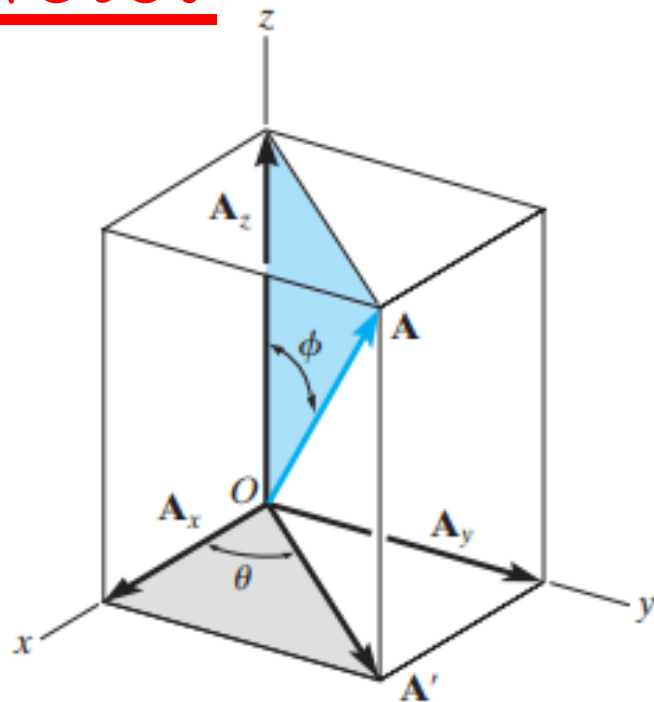
$$\cos \gamma = \frac{A_z}{A}$$

$$\mathbf{u}_A = \frac{\mathbf{A}}{A} = \frac{A_x}{A}\mathbf{i} + \frac{A_y}{A}\mathbf{j} + \frac{A_z}{A}\mathbf{k}$$

$$\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$$

$$\begin{aligned} \mathbf{A} &= A\mathbf{u}_A \\ &= A \cos \alpha \mathbf{i} + A \cos \beta \mathbf{j} + A \cos \gamma \mathbf{k} \\ &= A_x \mathbf{i} + A_y \mathbf{j} + A_z \mathbf{k} \end{aligned}$$

## Note:



Sometimes, the direction of  $\mathbf{A}$  can be specified using two angles,  $\theta$  and  $\phi$  (phi), such as shown in Fig. . The components of  $\mathbf{A}$  can then be determined by applying trigonometry first to the blue right triangle, which yields

$$A_z = A \cos \phi$$

and

$$A' = A \sin \phi$$

Now applying trigonometry to the gray shaded right triangle,

$$A_x = A' \cos \theta = A \sin \phi \cos \theta$$

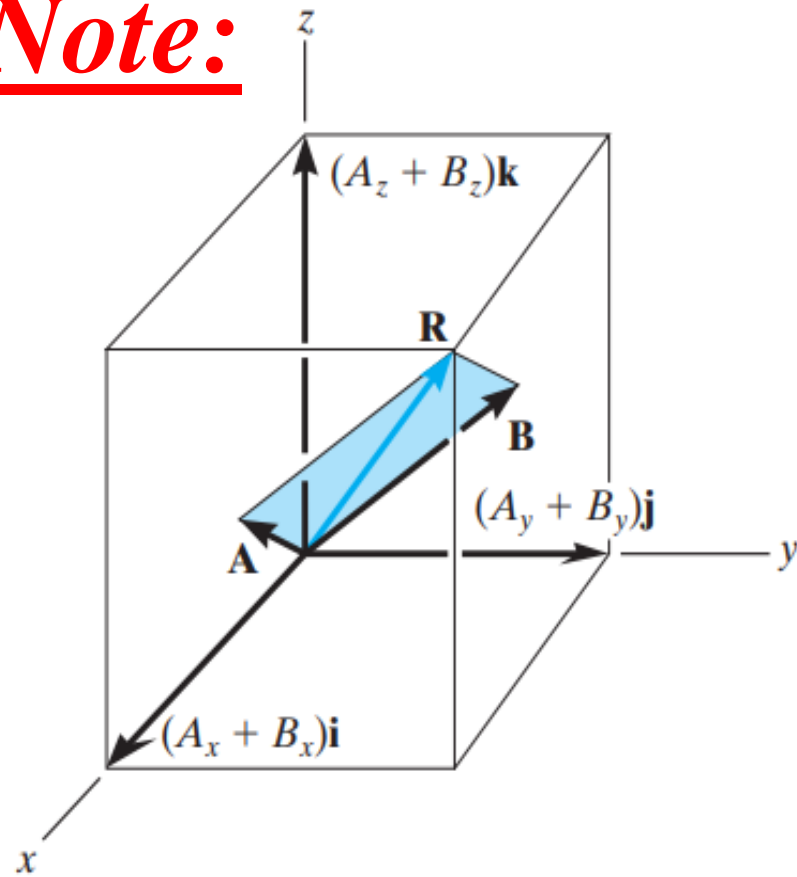
$$A_y = A' \sin \theta = A \sin \phi \sin \theta$$

Therefore  $\mathbf{A}$  written in Cartesian vector form becomes

$$\mathbf{A} = A \sin \phi \cos \theta \mathbf{i} + A \sin \phi \sin \theta \mathbf{j} + A \cos \phi \mathbf{k}$$

You should not memorize this equation, rather it is important to understand how the components were determined using trigonometry.

## Note:



The addition (or subtraction) of two or more vectors is greatly simplified if the vectors are expressed in terms of their Cartesian components. For example, if  $\mathbf{A} = A_x\mathbf{i} + A_y\mathbf{j} + A_z\mathbf{k}$  and  $\mathbf{B} = B_x\mathbf{i} + B_y\mathbf{j} + B_z\mathbf{k}$ , Fig. then the resultant vector, **R**, has components which are the scalar sums of the **i**, **j**, **k** components of **A** and **B**, i.e.,

$$\mathbf{R} = \mathbf{A} + \mathbf{B} = (A_x + B_x)\mathbf{i} + (A_y + B_y)\mathbf{j} + (A_z + B_z)\mathbf{k}$$

If this is generalized and applied to a system of several concurrent forces, then the force resultant is the vector sum of all the forces in the system and can be written as

$$\mathbf{F}_R = \Sigma \mathbf{F} = \Sigma F_x\mathbf{i} + \Sigma F_y\mathbf{j} + \Sigma F_z\mathbf{k}$$

Here  $\Sigma F_x$ ,  $\Sigma F_y$ , and  $\Sigma F_z$  represent the algebraic sums of the respective *x*, *y*, *z* or **i**, **j**, **k** components of each force in the system.

## Important Points

- Cartesian vector analysis is often used to solve problems in three dimensions.
- The positive directions of the  $x$ ,  $y$ ,  $z$  axes are defined by the Cartesian unit vectors  $\mathbf{i}$ ,  $\mathbf{j}$ ,  $\mathbf{k}$ , respectively.
- The *magnitude* of a Cartesian vector is  $A = \sqrt{A_x^2 + A_y^2 + A_z^2}$ .
- The *direction* of a Cartesian vector is specified using coordinate direction angles  $\alpha$ ,  $\beta$ ,  $\gamma$  which the tail of the vector makes with the positive  $x$ ,  $y$ ,  $z$  axes, respectively. The components of the unit vector  $\mathbf{u}_A = \mathbf{A}/A$  represent the direction cosines of  $\alpha$ ,  $\beta$ ,  $\gamma$ . Only two of the angles  $\alpha$ ,  $\beta$ ,  $\gamma$  have to be specified. The third angle is determined from the relationship  $\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$ .
- Sometimes the direction of a vector is defined using the two angles  $\theta$  and  $\phi$  as in Fig. 2–28. In this case the vector components are obtained by vector resolution using trigonometry.
- To find the *resultant* of a concurrent force system, express each force as a Cartesian vector and add the  $\mathbf{i}$ ,  $\mathbf{j}$ ,  $\mathbf{k}$  components of all the forces in the system.

**Example 1:** Express the force **F** shown in figure as a Cartesian vector.

**Solution:**

Since only two coordinate direction angles are specified, the third angle  $\alpha$  must be determined from Eq.i.e.,

$$\begin{aligned}\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma &= 1 \\ \cos^2 \alpha + \cos^2 60^\circ + \cos^2 45^\circ &= 1 \\ \cos \alpha &= \sqrt{1 - (0.5)^2 - (0.707)^2} = \pm 0.5\end{aligned}$$

Hence, two possibilities exist, namely,

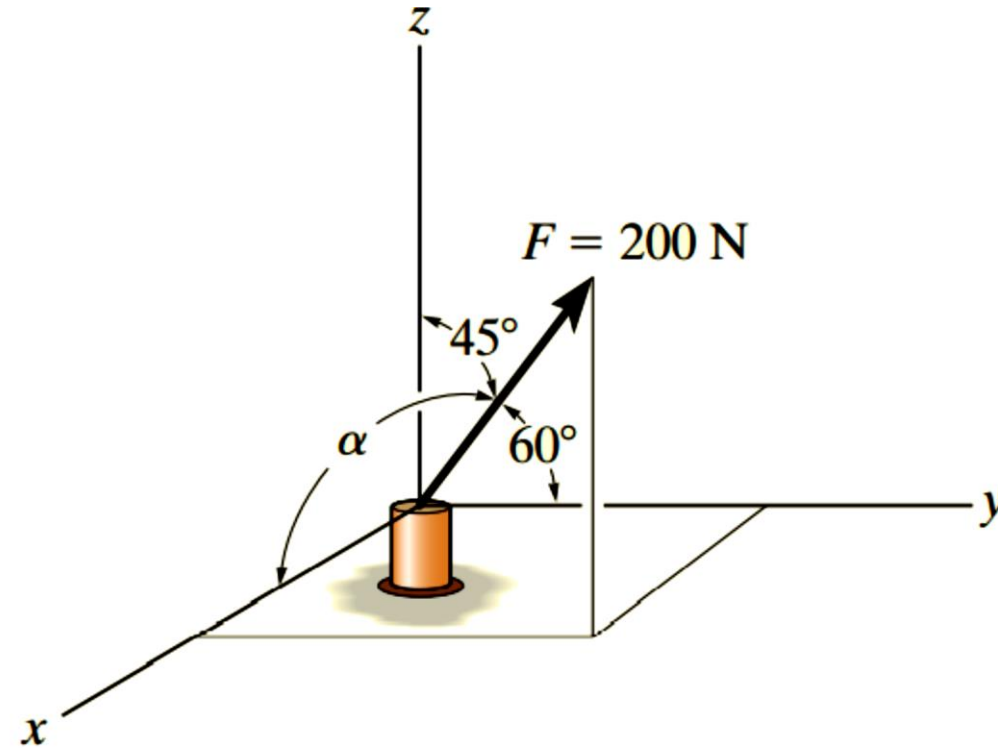
$$\alpha = \cos^{-1}(0.5) = 60^\circ \quad \text{or} \quad \alpha = \cos^{-1}(-0.5) = 120^\circ$$

By inspection it is necessary that  $\alpha = 60^\circ$ , since  $F_x$  must be in the  $+x$  direction.

Using Eq. , with  $F = 200$  N, we have

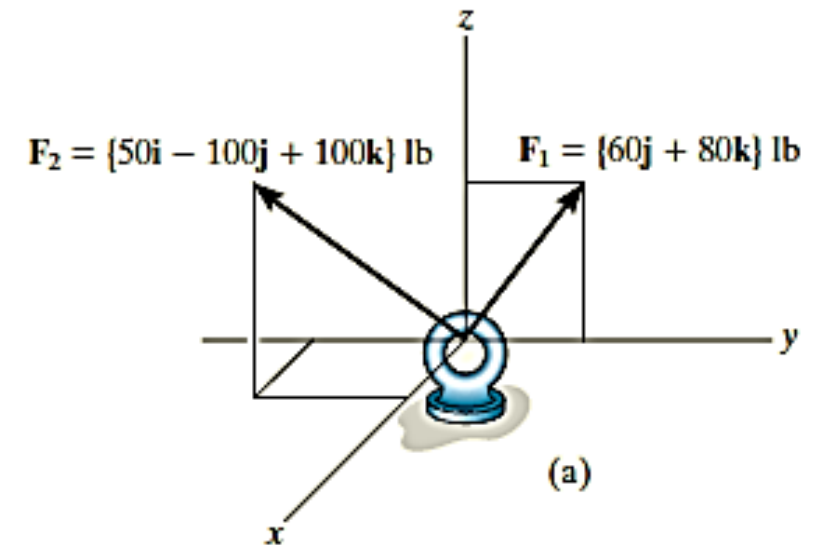
$$\begin{aligned}\mathbf{F} &= F \cos \alpha \mathbf{i} + F \cos \beta \mathbf{j} + F \cos \gamma \mathbf{k} \\ &= (200 \cos 60^\circ \text{ N})\mathbf{i} + (200 \cos 60^\circ \text{ N})\mathbf{j} + (200 \cos 45^\circ \text{ N})\mathbf{k} \\ &= \{100.0\mathbf{i} + 100.0\mathbf{j} + 141.4\mathbf{k}\} \text{ N}\end{aligned}$$

*Ans.*



## Example 2:

Determine the magnitude and the coordinate direction angles of the resultant force acting on the ring in Figure a.



### SOLUTION

Since each force is represented in Cartesian vector form, the resultant force, shown in is

$$\begin{aligned} F_R = \Sigma F &= F_1 + F_2 = \{60\mathbf{j} + 80\mathbf{k}\} \text{ lb} + \{50\mathbf{i} - 100\mathbf{j} + 100\mathbf{k}\} \text{ lb} \\ &= \{50\mathbf{i} - 40\mathbf{j} + 180\mathbf{k}\} \text{ lb} \end{aligned}$$

The magnitude of  $F_R$  is

$$\begin{aligned} F_R &= \sqrt{(50 \text{ lb})^2 + (-40 \text{ lb})^2 + (180 \text{ lb})^2} = 191.0 \text{ lb} \\ &= 191 \text{ lb} \end{aligned}$$

*Ans.*

The coordinate direction angles  $\alpha, \beta, \gamma$  are determined from the components of the unit vector acting in the direction of  $\mathbf{F}_R$ .

$$\begin{aligned}\mathbf{u}_{F_R} &= \frac{\mathbf{F}_R}{F_R} = \frac{50}{191.0}\mathbf{i} - \frac{40}{191.0}\mathbf{j} + \frac{180}{191.0}\mathbf{k} \\ &= 0.2617\mathbf{i} - 0.2094\mathbf{j} + 0.9422\mathbf{k}\end{aligned}$$

so that

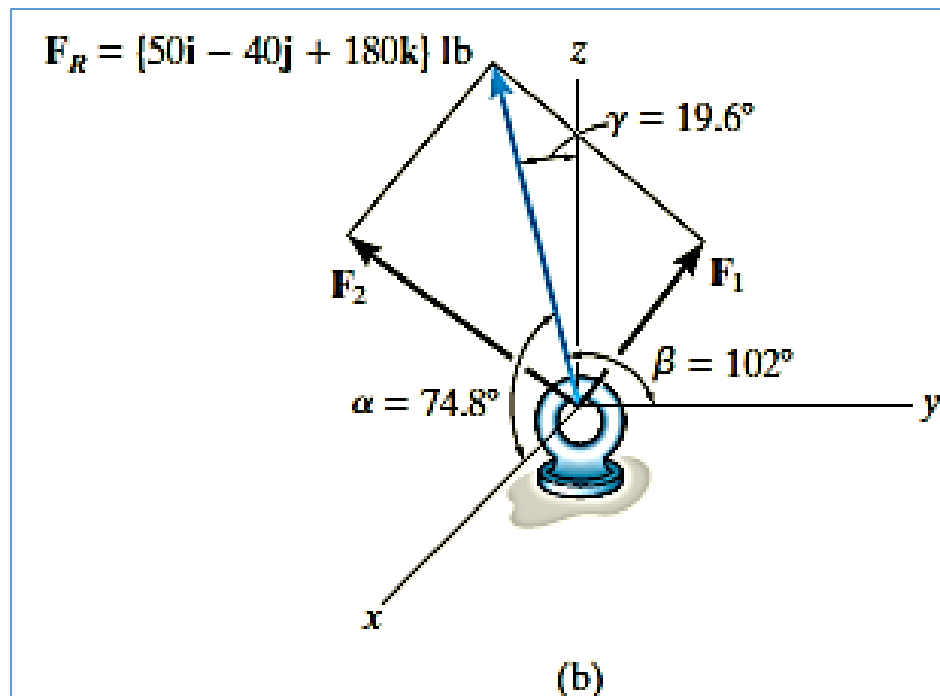
$$\cos \alpha = 0.2617 \quad \alpha = 74.8^\circ$$

$$\cos \beta = -0.2094 \quad \beta = 102^\circ$$

$$\cos \gamma = 0.9422 \quad \gamma = 19.6^\circ$$

These angles are shown in Fig. *b*.

**NOTE:** In particular, notice that  $\beta > 90^\circ$  since the  $\mathbf{j}$  component of  $\mathbf{u}_{F_R}$  is negative.



**Example 3:** Express the force **F** shown in Fig. *a* as a Cartesian vector and direction angles of the resultant force.

**Solution:**

$$F_z = 100 \sin 60^\circ \text{ lb} = 86.6 \text{ lb}$$

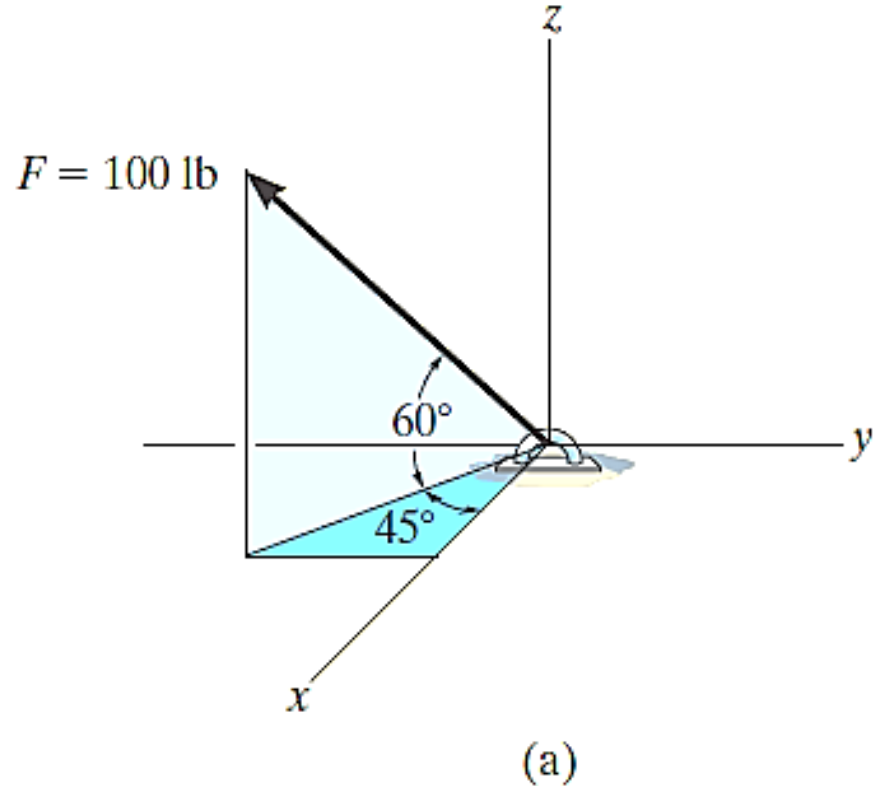
$$F' = 100 \cos 60^\circ \text{ lb} = 50 \text{ lb}$$

$$F_x = F' \cos 45^\circ = 50 \cos 45^\circ \text{ lb} = 35.4 \text{ lb}$$

$$F_y = F' \sin 45^\circ = 50 \sin 45^\circ \text{ lb} = 35.4 \text{ lb}$$

Realizing that **F<sub>y</sub>** has a direction defined by **-j**, we have

$$\mathbf{F} = \{35.4\mathbf{i} - 35.4\mathbf{j} + 86.6\mathbf{k}\} \text{ lb}$$



*Ans.*

$$F = \sqrt{F_x^2 + F_y^2 + F_z^2}$$

$$= \sqrt{(35.4)^2 + (35.4)^2 + (86.6)^2} = 100 \text{ lb}$$

If needed, the coordinate direction angles of  $\mathbf{F}$  can be determined from the components of the unit vector acting in the direction of  $\mathbf{F}$ . Hence,

$$\mathbf{u} = \frac{\mathbf{F}}{F} = \frac{F_x}{F}\mathbf{i} + \frac{F_y}{F}\mathbf{j} + \frac{F_z}{F}\mathbf{k}$$

$$= \frac{35.4}{100}\mathbf{i} - \frac{35.4}{100}\mathbf{j} + \frac{86.6}{100}\mathbf{k}$$

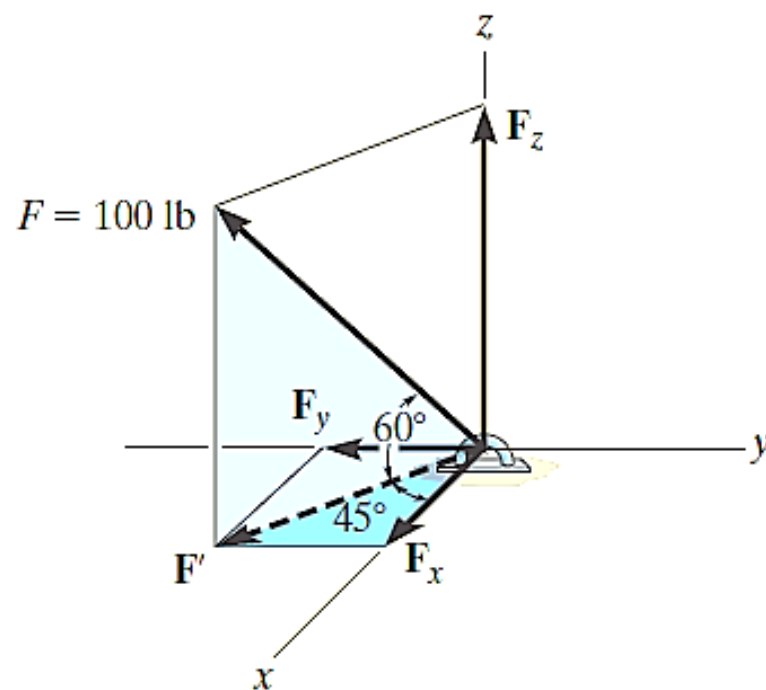
$$= 0.354\mathbf{i} - 0.354\mathbf{j} + 0.866\mathbf{k}$$

so that

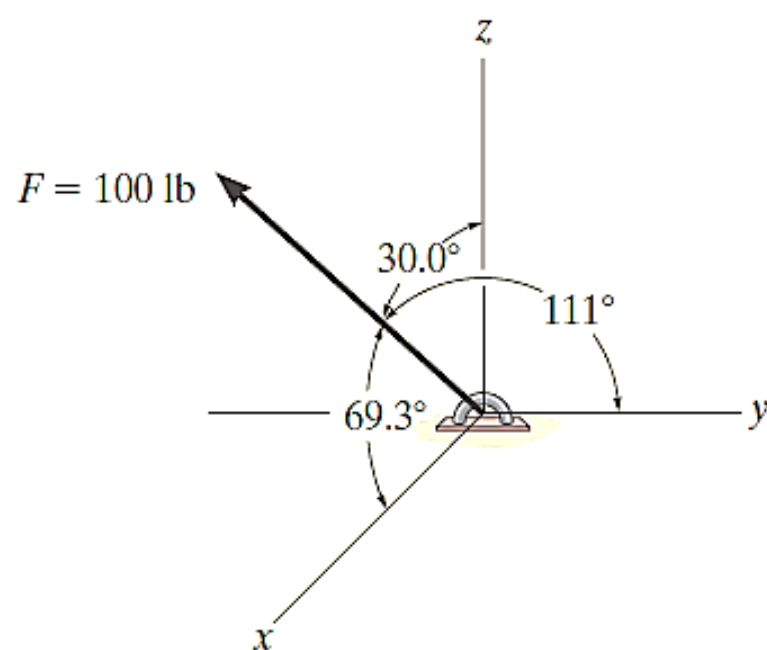
$$\alpha = \cos^{-1}(0.354) = 69.3^\circ$$

$$\beta = \cos^{-1}(-0.354) = 111^\circ$$

$$\gamma = \cos^{-1}(0.866) = 30.0^\circ$$



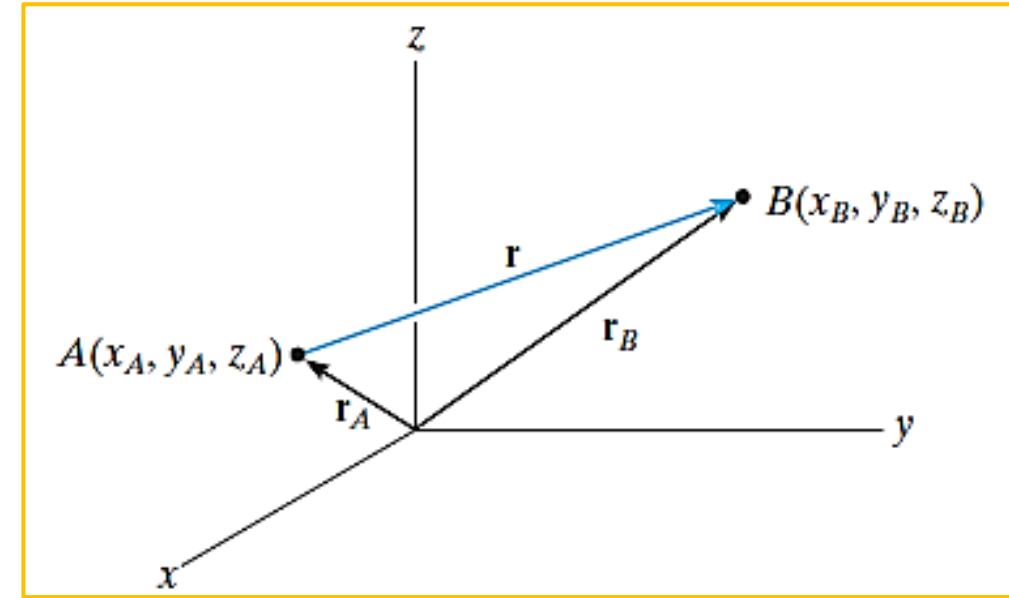
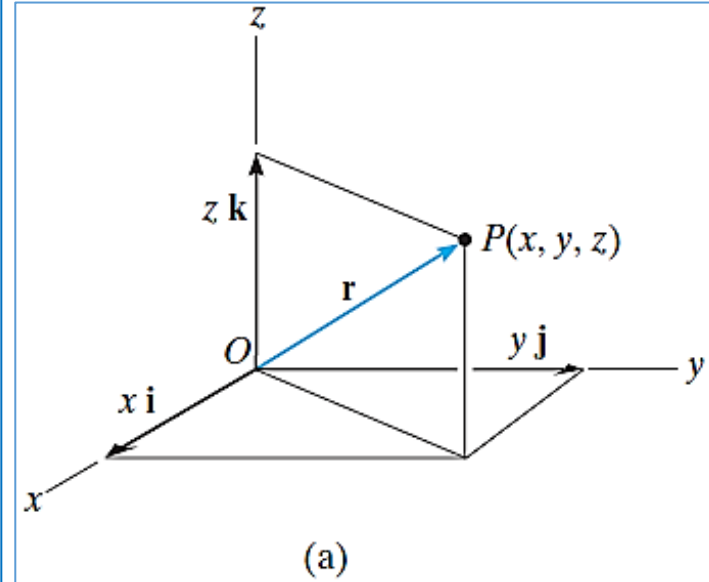
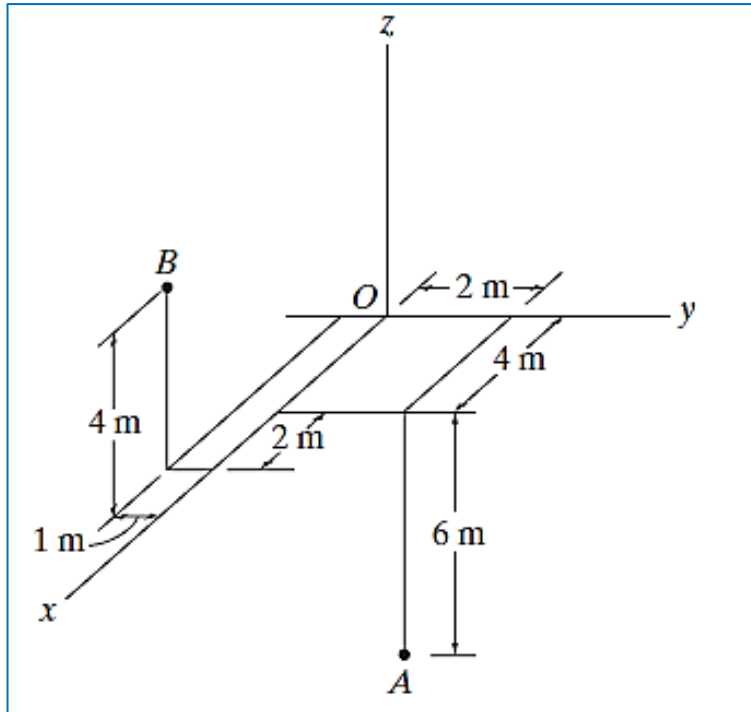
b)



(c)

- **Position Vectors ( $\mathbf{r}$ ):** (specify the forces by two points on the line of action)

Defined as a fixed vector which locates a point in space relative to another point.



$$\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$

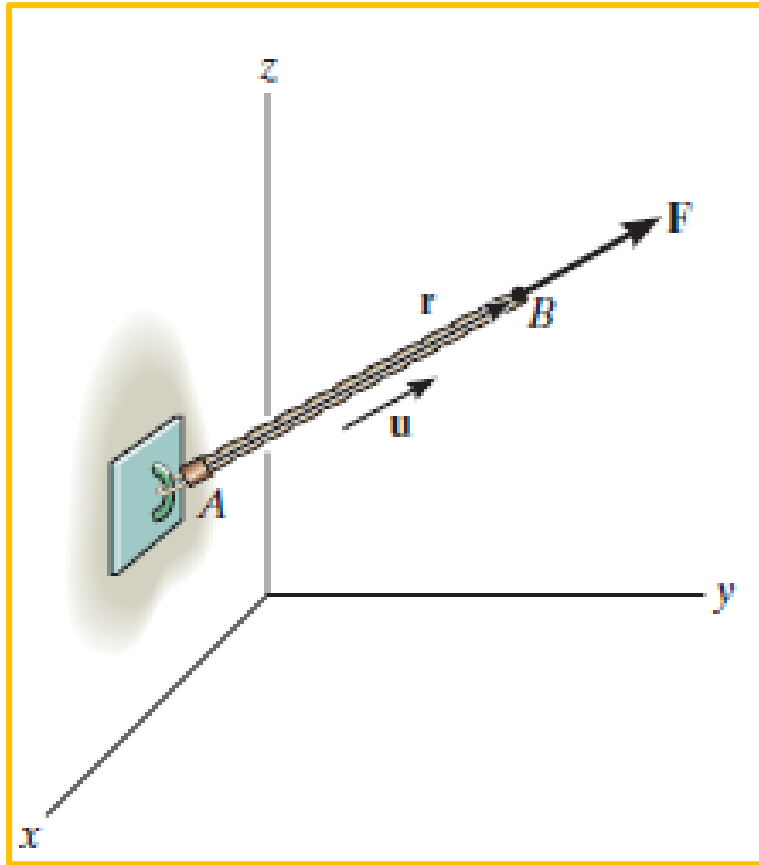
$$\mathbf{r}_A + \mathbf{r} = \mathbf{r}_B$$

$$\mathbf{r} = \mathbf{r}_B - \mathbf{r}_A = (x_B\mathbf{i} + y_B\mathbf{j} + z_B\mathbf{k}) - (x_A\mathbf{i} + y_A\mathbf{j} + z_A\mathbf{k})$$

or

$$\mathbf{r} = (x_B - x_A)\mathbf{i} + (y_B - y_A)\mathbf{j} + (z_B - z_A)\mathbf{k}$$

- **Force Vector Directed Along a Line**



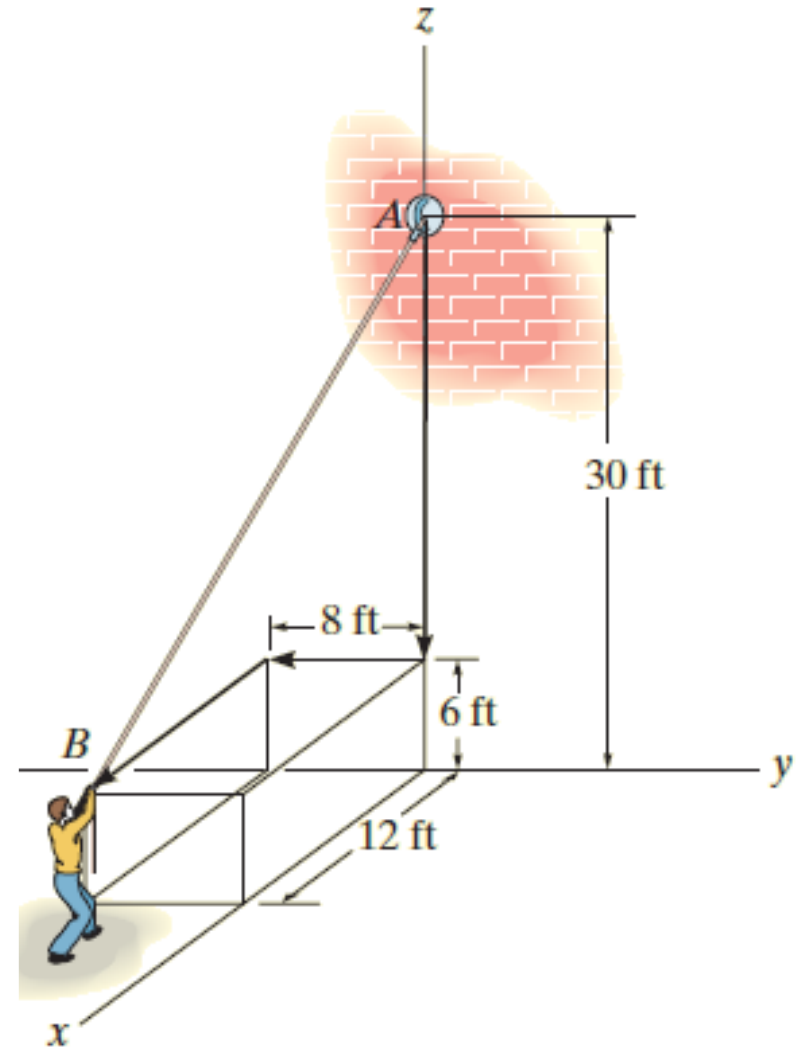
$$\mathbf{F} = F\mathbf{u} = F \frac{\mathbf{r}_{AB}}{|\mathbf{r}_{AB}|} = F \frac{(x_B - x_A)\mathbf{i} + (y_B - y_A)\mathbf{j} + (z_B - z_A)\mathbf{k}}{\sqrt{(x_B - x_A)^2 + (y_B - y_A)^2 + (z_B - z_A)^2}}$$

## Important Points

- A position vector locates one point in space relative to another point.
- The easiest way to formulate the components of a position vector is to determine the distance and direction that must be traveled along the  $x$ ,  $y$ ,  $z$  directions—going from the tail to the head of the vector.
- A force  $\mathbf{F}$  acting in the direction of a position vector  $\mathbf{r}$  can be represented in Cartesian form if the unit vector  $\mathbf{u}$  of the position vector is determined and it is multiplied by the magnitude of the force, i.e.,  $\mathbf{F} = F\mathbf{u} = F(\mathbf{r}/r)$ .

## Example 4//

The man shown in Figure pulls on the cord with a force of 70 lb. Represent this force acting on the support A as a Cartesian vector and determine its direction.



## Solution//

$$\mathbf{r} = \{12\mathbf{i} - 8\mathbf{j} - 24\mathbf{k}\} \text{ ft}$$

The magnitude of  $\mathbf{r}$ , which represents the *length* of cord  $AB$ , is

$$r = \sqrt{(12 \text{ ft})^2 + (-8 \text{ ft})^2 + (-24 \text{ ft})^2} = 28 \text{ ft}$$

Forming the unit vector that defines the direction and sense of both  $\mathbf{r}$  and  $\mathbf{F}$ , we have

$$\mathbf{u} = \frac{\mathbf{r}}{r} = \frac{12}{28}\mathbf{i} - \frac{8}{28}\mathbf{j} - \frac{24}{28}\mathbf{k}$$

Since  $\mathbf{F}$  has a *magnitude* of 70 lb and a *direction* specified by  $\mathbf{u}$ , then

$$\begin{aligned}\mathbf{F} &= F\mathbf{u} = 70 \text{ lb} \left( \frac{12}{28}\mathbf{i} - \frac{8}{28}\mathbf{j} - \frac{24}{28}\mathbf{k} \right) \\ &= \{30\mathbf{i} - 20\mathbf{j} - 60\mathbf{k}\} \text{ lb} \quad \text{Ans.}\end{aligned}$$

## Solution cont.//

From the components of the unit vector:

$$\alpha = \cos^{-1}\left(\frac{12}{28}\right) = 64.6^\circ$$

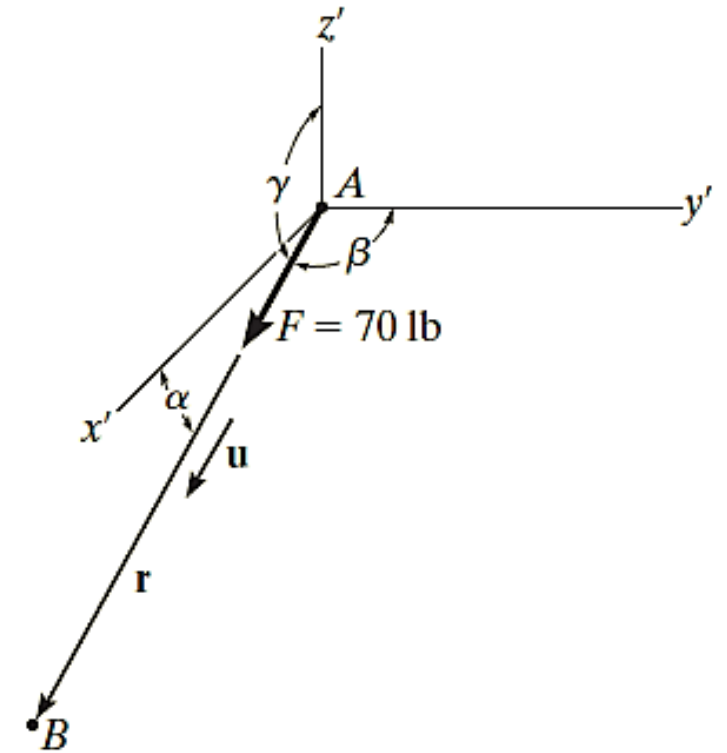
$$\beta = \cos^{-1}\left(\frac{-8}{28}\right) = 107^\circ$$

$$\gamma = \cos^{-1}\left(\frac{-24}{28}\right) = 149^\circ$$

*Ans.*

*Ans.*

*Ans.*



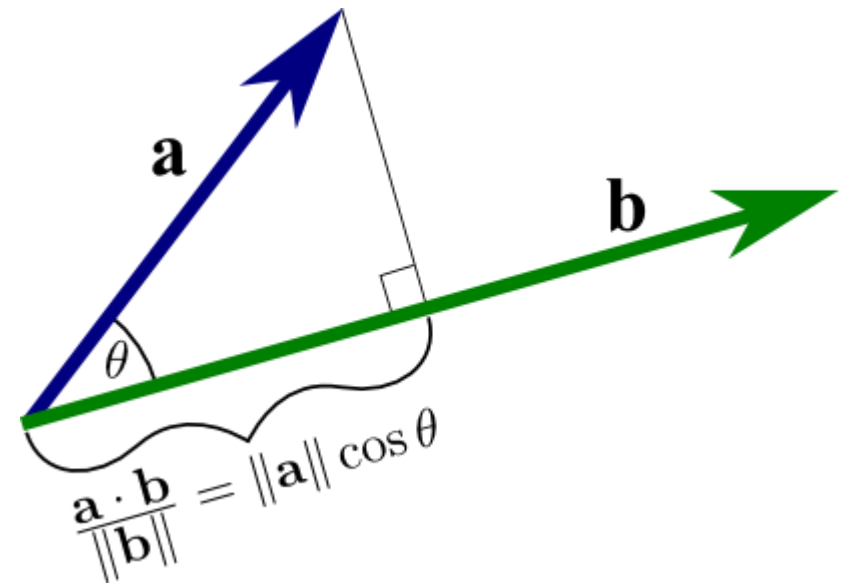
- **Dot Product** *(specify the forces by angle which oriented the line of action)*
- The dot product between two vectors **A** and **B** yields a scalar. If A and B are expressed in Cartesian vector form, then the dot product is the sum of the products of their *x*, *y*, and *z* components.
- The dot product is used to determine the angle between two vectors or the projection of a vector in a specified direction.

$$\mathbf{A} \cdot \mathbf{B} = AB \cos \theta$$

where  $0^\circ \leq \theta \leq 180^\circ$

### Laws of Operation.

1. Commutative law:  $\mathbf{A} \cdot \mathbf{B} = \mathbf{B} \cdot \mathbf{A}$
2. Multiplication by a scalar:  $a(\mathbf{A} \cdot \mathbf{B}) = (a\mathbf{A}) \cdot \mathbf{B} = \mathbf{A} \cdot (a\mathbf{B})$
3. Distributive law:  $\mathbf{A} \cdot (\mathbf{B} + \mathbf{D}) = (\mathbf{A} \cdot \mathbf{B}) + (\mathbf{A} \cdot \mathbf{D})$



## Cartesian Vector Formulation.

$$\begin{aligned}\mathbf{A} \cdot \mathbf{B} &= (A_x \mathbf{i} + A_y \mathbf{j} + A_z \mathbf{k}) \cdot (B_x \mathbf{i} + B_y \mathbf{j} + B_z \mathbf{k}) \\ &= A_x B_x (\mathbf{i} \cdot \mathbf{i}) + A_x B_y (\mathbf{i} \cdot \mathbf{j}) + A_x B_z (\mathbf{i} \cdot \mathbf{k}) \\ &\quad + A_y B_x (\mathbf{j} \cdot \mathbf{i}) + A_y B_y (\mathbf{j} \cdot \mathbf{j}) + A_y B_z (\mathbf{j} \cdot \mathbf{k}) \\ &\quad + A_z B_x (\mathbf{k} \cdot \mathbf{i}) + A_z B_y (\mathbf{k} \cdot \mathbf{j}) + A_z B_z (\mathbf{k} \cdot \mathbf{k})\end{aligned}$$

Carrying out the dot-product operations, the final result becomes

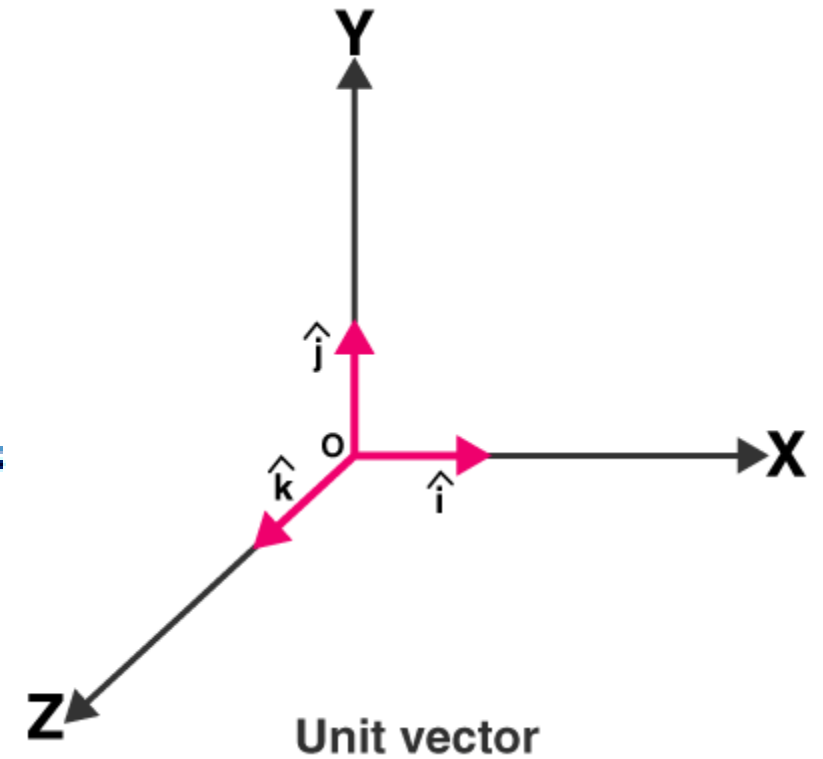
$$\mathbf{A} \cdot \mathbf{B} = A_x B_x + A_y B_y + A_z B_z$$

$$\mathbf{i} \cdot \mathbf{i} = (1)(1) \cos 0^\circ = 1$$

$$\mathbf{i} \cdot \mathbf{j} = (1)(1) \cos 90^\circ = 0.$$

$$\begin{aligned}\vec{i} \cdot \vec{i} &= 1 \\ \vec{j} \cdot \vec{j} &= 1 \\ \vec{k} \cdot \vec{k} &= 1\end{aligned}$$

$$\begin{aligned}\vec{i} \cdot \vec{j} &= 0 \\ \vec{j} \cdot \vec{k} &= 0 \\ \vec{k} \cdot \vec{i} &= 0\end{aligned}$$



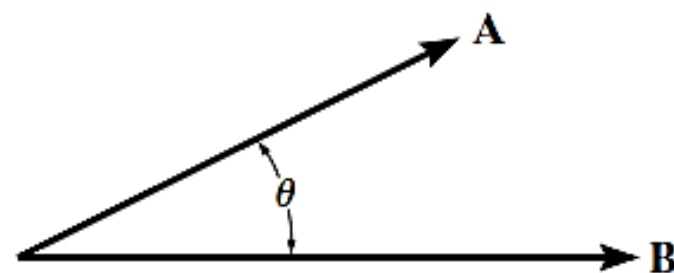
**Applications.** The dot product has two important applications in mechanics.

- *The angle formed between two vectors or intersecting lines.*

$$\theta = \cos^{-1}\left(\frac{\mathbf{A} \cdot \mathbf{B}}{AB}\right) \quad 0^\circ \leq \theta \leq 180^\circ$$

notice that if

$\mathbf{A} \cdot \mathbf{B} = 0$ ,  $\theta = \cos^{-1} 0 = 90^\circ$  so that  $\mathbf{A}$  will be *perpendicular* to  $\mathbf{B}$ .



- *The components of a vector parallel and perpendicular to a line.*

$$A_a = A \cos \theta = \mathbf{A} \cdot \mathbf{u}_a$$

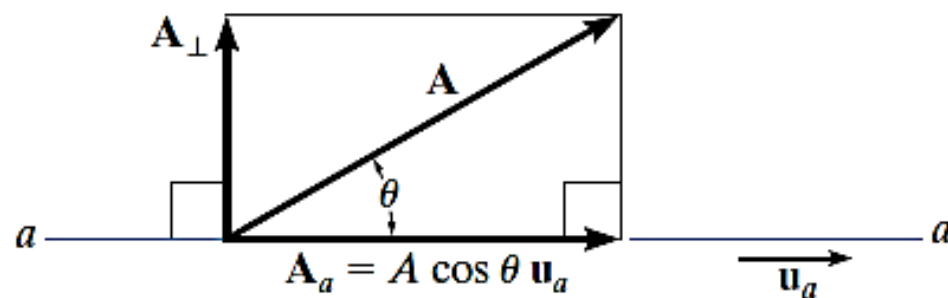
Since  $\mathbf{A} = \mathbf{A}_a + \mathbf{A}_\perp$ , then  $\mathbf{A}_\perp = \mathbf{A} - \mathbf{A}_a$ .

$$\theta = \cos^{-1}(\mathbf{A} \cdot \mathbf{u}_a / A)$$

$$A_\perp = A \sin \theta$$

Pythagorean's theorem

$$A_\perp = \sqrt{A^2 - A_a^2}$$

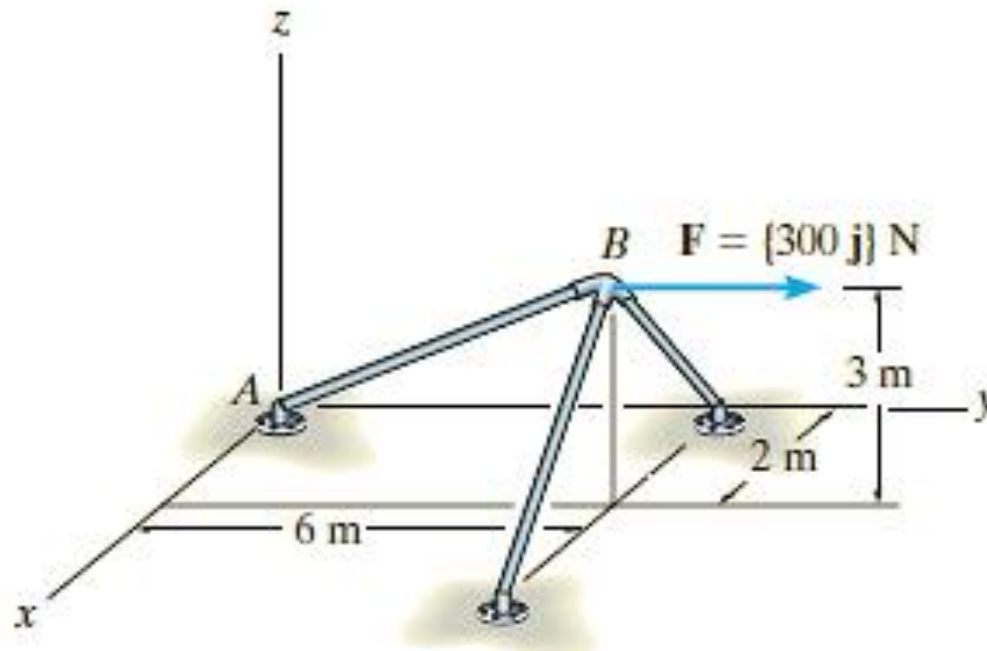


## Important Points

- The dot product is used to determine the angle between two vectors or the projection of a vector in a specified direction.
- If vectors **A** and **B** are expressed in Cartesian vector form, the dot product is determined by multiplying the respective  $x$ ,  $y$ ,  $z$  scalar components and algebraically adding the results, i.e.,  
$$\mathbf{A} \cdot \mathbf{B} = A_x B_x + A_y B_y + A_z B_z.$$
- From the definition of the dot product, the angle formed between the tails of vectors **A** and **B** is  $\theta = \cos^{-1}(\mathbf{A} \cdot \mathbf{B} / AB)$ .
- The magnitude of the projection of vector **A** along a line  $aa$  whose direction is specified by  $\mathbf{u}_a$  is determined from the dot product  $A_a = \mathbf{A} \cdot \mathbf{u}_a$ .

### Example 5:

The frame shown in Figure is subjected to a horizontal force  $F = \{300 \mathbf{j}\}$ . Determine the magnitude of the components of this force parallel and perpendicular to member AB .



## Solution:

The magnitude of the component of  $\mathbf{F}$  along  $AB$  is equal to the dot product of  $\mathbf{F}$  and the unit vector  $\mathbf{u}_B$ , which defines the direction of  $AB$ ,

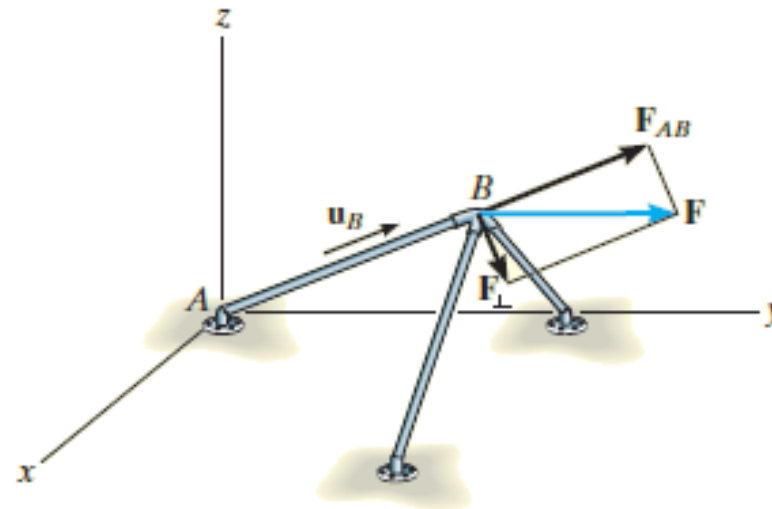
$$\mathbf{u}_B = \frac{\mathbf{r}_B}{r_B} = \frac{2\mathbf{i} + 6\mathbf{j} + 3\mathbf{k}}{\sqrt{(2)^2 + (6)^2 + (3)^2}} = 0.286\mathbf{i} + 0.857\mathbf{j} + 0.429\mathbf{k}$$

then

$$\begin{aligned} F_{AB} &= F \cos \theta = \mathbf{F} \cdot \mathbf{u}_B = (300\mathbf{j}) \cdot (0.286\mathbf{i} + 0.857\mathbf{j} + 0.429\mathbf{k}) \\ &= (0)(0.286) + (300)(0.857) + (0)(0.429) \\ &= 257.1 \text{ N} \end{aligned}$$

*Ans.*

Since the result is a positive scalar,  $F_{AB}$  has the same sense of direction as  $\mathbf{u}_B$ , Fig



## Solution cont.:

Expressing  $\mathbf{F}_{AB}$  in Cartesian vector form, we have

$$\begin{aligned}\mathbf{F}_{AB} &= F_{AB}\mathbf{u}_B = (257.1 \text{ N})(0.286\mathbf{i} + 0.857\mathbf{j} + 0.429\mathbf{k}) \\ &= \{73.5\mathbf{i} + 220\mathbf{j} + 110\mathbf{k}\} \text{ N}\end{aligned}$$

*Ans.*

The perpendicular component, Fig. is therefore

$$\begin{aligned}\mathbf{F}_{\perp} &= \mathbf{F} - \mathbf{F}_{AB} = 300\mathbf{j} - (73.5\mathbf{i} + 220\mathbf{j} + 110\mathbf{k}) \\ &= \{-73.5\mathbf{i} + 79.6\mathbf{j} - 110\mathbf{k}\} \text{ N}\end{aligned}$$

Its magnitude can be determined either from this vector or by using the Pythagorean theorem, Fig.

$$\begin{aligned}F_{\perp} &= \sqrt{F^2 - F_{AB}^2} = \sqrt{(300 \text{ N})^2 - (257.1 \text{ N})^2} \\ &= 155 \text{ N}\end{aligned}$$

*Ans.*

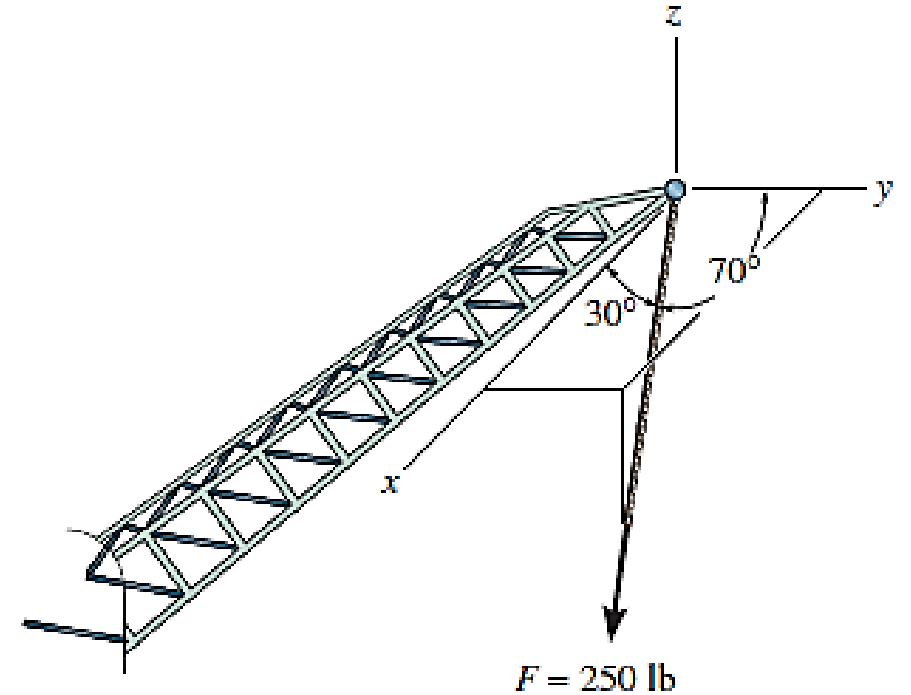
# Next Lecture:

- Moment of a Force - Scalar Formulation
- Cross Product
- Moment of a Force - Vector Formulation
- Solving Related examples

# Assignment 1:

(solve this problems then submit your answer)

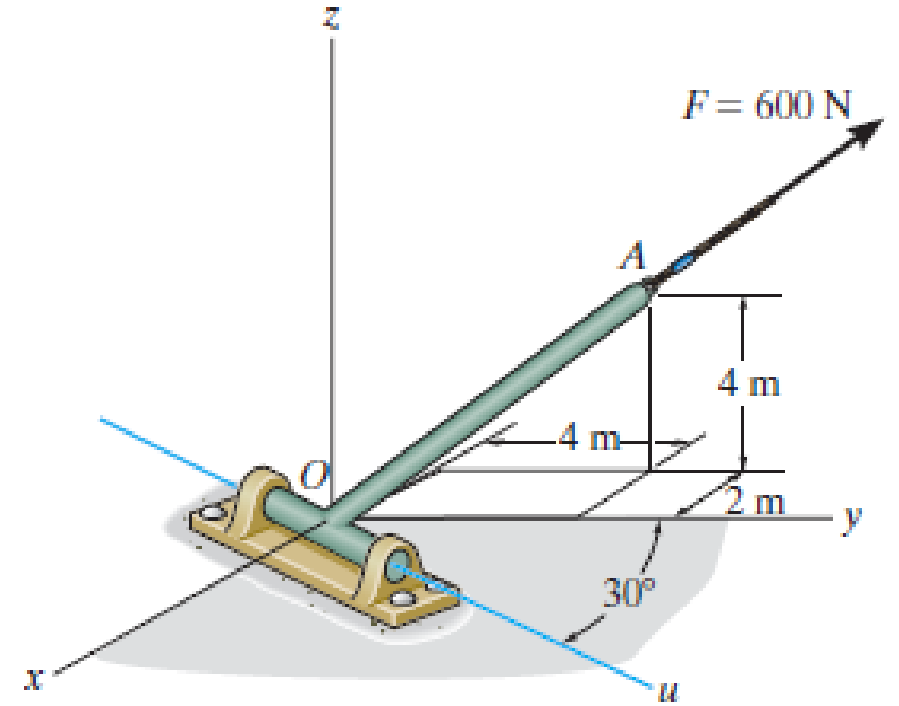
The cable at the end of the crane boom exerts a force of 250 *lb* on the boom as shown. Express **F** as a Cartesian vector.



## Assignment 2:

(solve this problems then submit your answer)

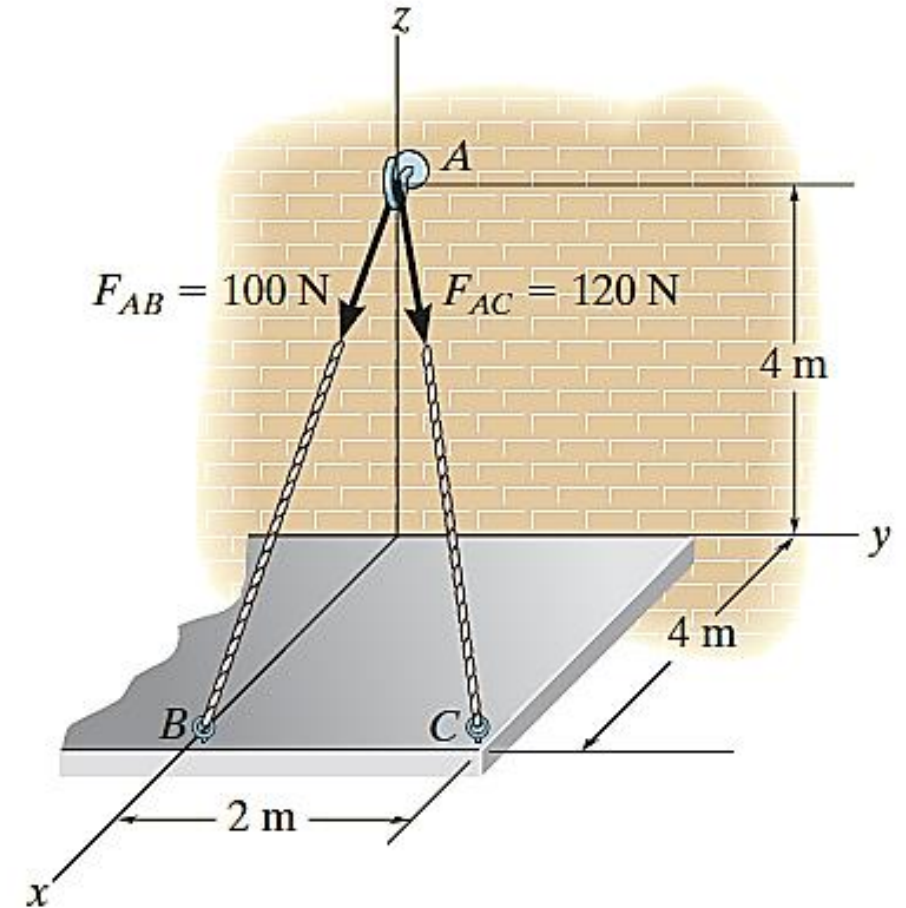
Determine the magnitude of the projection of force  $F = 600\text{ N}$  along the  $u$  axis.



# Assignment 3:

(solve this problems then submit your answer)

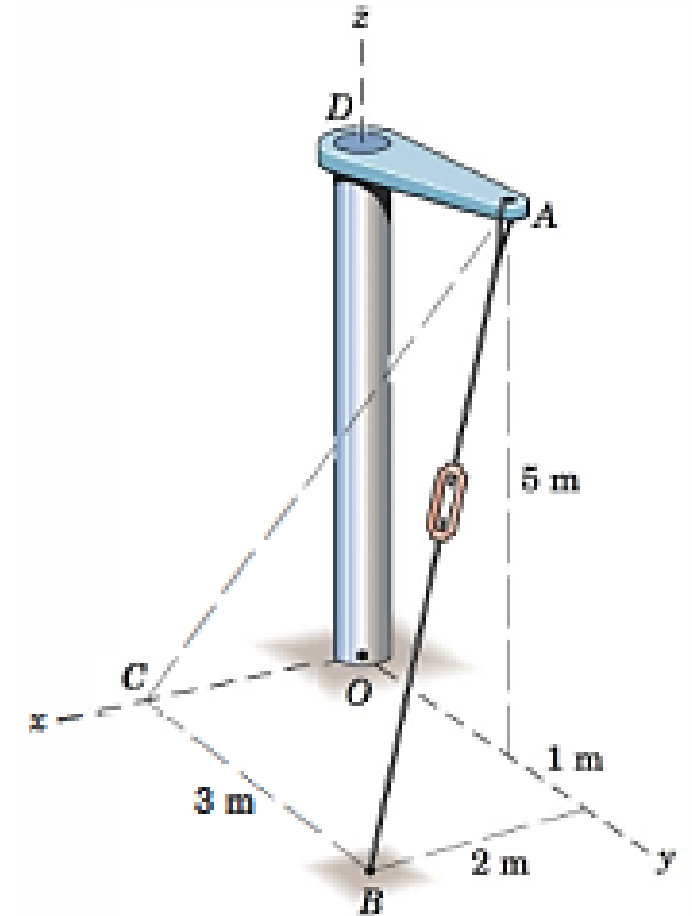
The roof is supported by cables as shown in the photo. If the cables exert forces  $F_{AB} = 100\text{ N}$  and  $F_{AC} = 120\text{ N}$  on the wall hook at A as shown in Fig., determine the resultant force acting at A. Express the result as a Cartesian vector.



# Assignment 4:

(solve this problems then submit your answer)

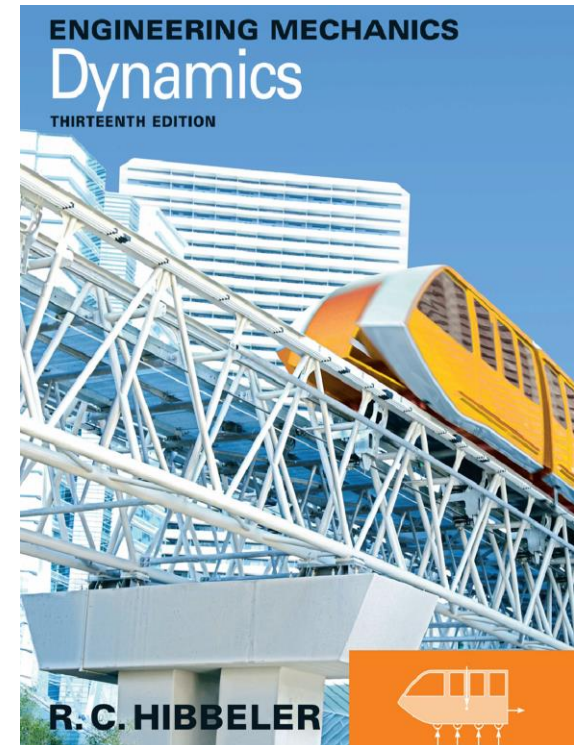
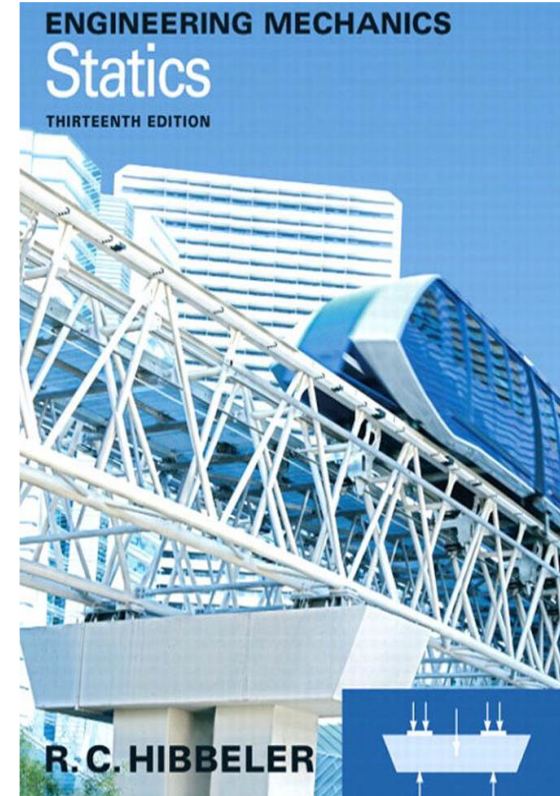
The turnbuckle is tightened until the tension in the cable AB equals  $2.4\text{ kN}$ . Determine the vector expression for the tension  $T$  as a force acting on member AD. Also find the magnitude of the projection of  $T$  along the line AC



# References:

Engineering Mechanics R.C.

Hibbeler 13<sup>th</sup> edition (Statics and Dynamics).



*The end of the lecture*  
*Enjoy your time*