



# Linear Algebra

## Lecture Notes 5

# Norm of Vectors and Dot Product

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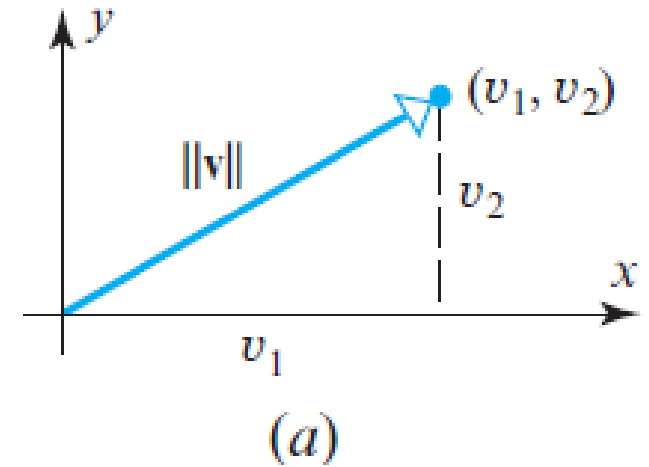
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# Norm of a Vector

The length of a vector  $\mathbf{v}$  is denoted by  $\|\mathbf{v}\|$ , which is read as the *norm* of  $\mathbf{v}$ , the *length* of  $\mathbf{v}$ , or the *magnitude* of  $\mathbf{v}$ .

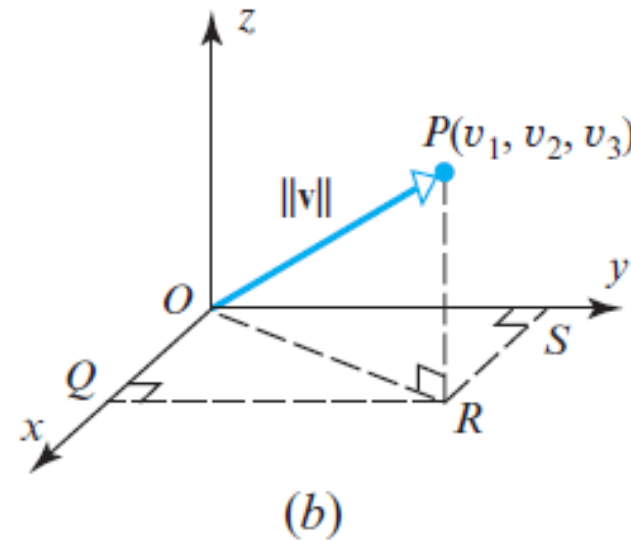
The norm of a vector  $(v_1, v_2)$  in  $R^2$  is

$$\|\mathbf{v}\| = \sqrt{v_1^2 + v_2^2}$$



Similarly, for a vector  $(v_1, v_2, v_3)$  in  $R^3$

$$\|\mathbf{v}\| = \sqrt{v_1^2 + v_2^2 + v_3^2}$$



**DEFINITION** If  $\mathbf{v} = (v_1, v_2, \dots, v_n)$  is a vector in  $R^n$ , then the *norm* of  $\mathbf{v}$  (also called the *length* of  $\mathbf{v}$  or the *magnitude* of  $\mathbf{v}$ ) is denoted by  $\|\mathbf{v}\|$ , and is defined by the formula

$$\|\mathbf{v}\| = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$$

**Examples:**

Evaluate the given expression with  $\mathbf{u} = (2, -2, 3)$ ,  $\mathbf{v} = (1, -3, 4)$ ,  $\mathbf{w} = (3, 6, -4)$ .

(a)  $\|\mathbf{u} + \mathbf{v}\|$

(b)  $\|\mathbf{u}\| + \|\mathbf{v}\|$

(c)  $\|-2\mathbf{u} + 2\mathbf{v}\|$

(d)  $\|3\mathbf{u} - 5\mathbf{v} + \mathbf{w}\|$

## Unit Vectors

A vector of norm 1 is called a **unit vector**. If  $\mathbf{v}$  is any nonzero vector in  $R^n$ , then

$$\mathbf{u} = \frac{1}{\|\mathbf{v}\|} \mathbf{v}$$

### Example: Normalizing a Vector

Find the unit vector  $\mathbf{u}$  that has the same direction as  $\mathbf{v} = (2, 2, -1)$ .

**Solution** The vector  $\mathbf{v}$  has length

$$\|\mathbf{v}\| = \sqrt{2^2 + 2^2 + (-1)^2} = 3$$

Thus, .

$$\mathbf{u} = \frac{1}{3}(2, 2, -1) = \left(\frac{2}{3}, \frac{2}{3}, -\frac{1}{3}\right)$$

As a check, you may want to confirm that  $\|\mathbf{u}\| = 1$ .

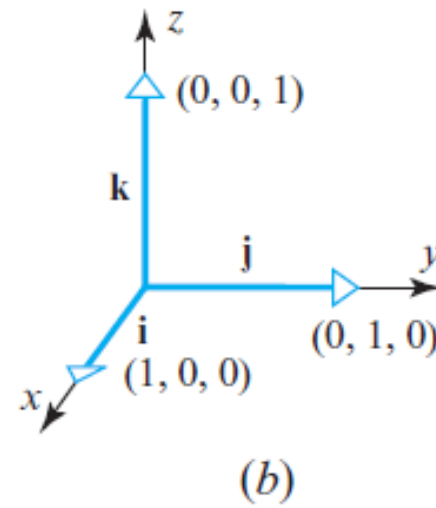
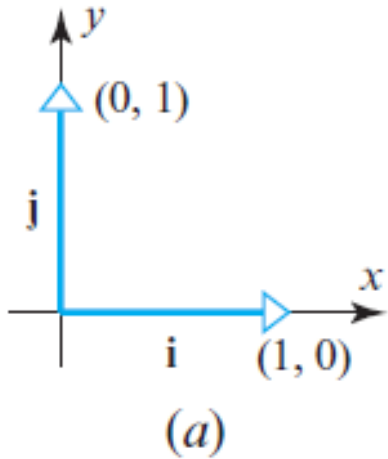
## The Standard Unit Vectors

The unit vectors in the positive directions of the coordinate axes are called the ***standard unit vectors***. In  $R^2$  these vectors are denoted by

$$\mathbf{i} = (1, 0) \quad \text{and} \quad \mathbf{j} = (0, 1)$$

and in  $R^3$  by

$$\mathbf{i} = (1, 0, 0), \quad \mathbf{j} = (0, 1, 0), \quad \text{and} \quad \mathbf{k} = (0, 0, 1)$$



Moreover, we can generalize these formulas to  $R^n$  by defining the *standard unit vectors in  $R^n$*  to be

$$\mathbf{e}_1 = (1, 0, 0, \dots, 0), \quad \mathbf{e}_2 = (0, 1, 0, \dots, 0), \dots, \quad \mathbf{e}_n = (0, 0, 0, \dots, 1)$$

in which case every vector  $\mathbf{v} = (v_1, v_2, \dots, v_n)$  in  $R^n$  can be expressed as

$$\mathbf{v} = (v_1, v_2, \dots, v_n) = v_1\mathbf{e}_1 + v_2\mathbf{e}_2 + \dots + v_n\mathbf{e}_n$$

### Linear Combinations of Standard Unit Vectors

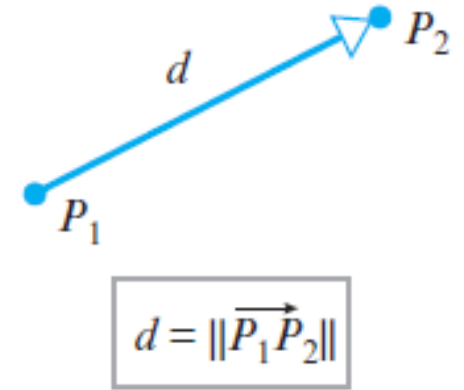
$$(2, -3, 4) = 2\mathbf{i} - 3\mathbf{j} + 4\mathbf{k}$$

$$(7, 3, -4, 5) = 7\mathbf{e}_1 + 3\mathbf{e}_2 - 4\mathbf{e}_3 + 5\mathbf{e}_4$$

## Distance in $R^n$

If  $P_1(x_1, y_1)$  and  $P_2(x_2, y_2)$  are points in  $R^2$

$$d = \|\overrightarrow{P_1P_2}\| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$



Similarly, the distance between the points  $P_1(x_1, y_1, z_1)$  and  $P_2(x_2, y_2, z_2)$  in 3-space is

$$d(\mathbf{u}, \mathbf{v}) = \|\overrightarrow{P_1P_2}\| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

**DEFINITION** If  $\mathbf{u} = (u_1, u_2, \dots, u_n)$  and  $\mathbf{v} = (v_1, v_2, \dots, v_n)$  are points in  $R^n$ , then we denote the *distance* between  $\mathbf{u}$  and  $\mathbf{v}$  by  $d(\mathbf{u}, \mathbf{v})$  and define it to be

$$d(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\| = \sqrt{(u_1 - v_1)^2 + (u_2 - v_2)^2 + \dots + (u_n - v_n)^2}$$

Example: If  $\mathbf{u} = (1, 3, -2, 7)$  and  $\mathbf{v} = (0, 7, 2, 2)$

then the distance between  $\mathbf{u}$  and  $\mathbf{v}$  is

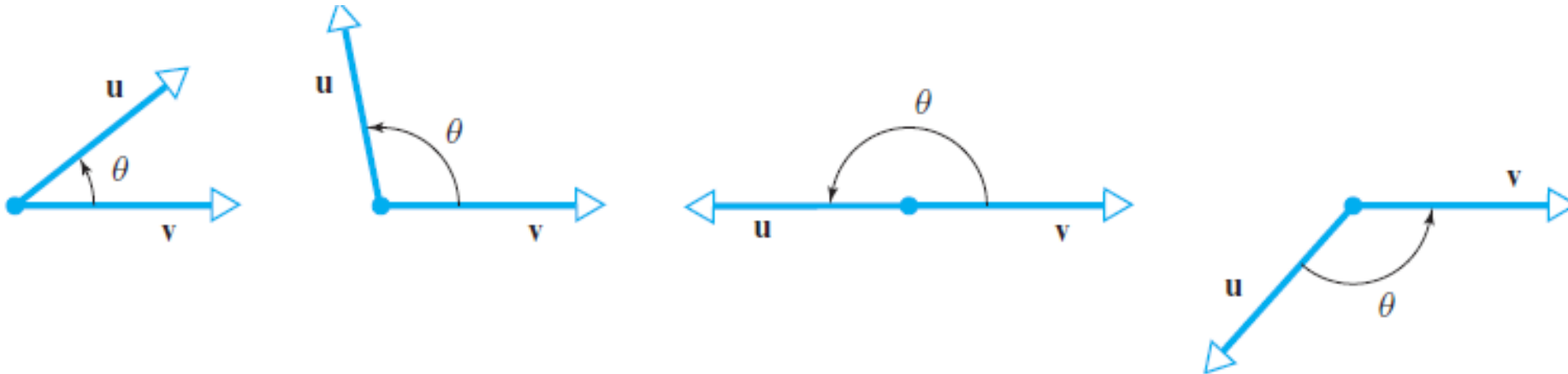
$$d(\mathbf{u}, \mathbf{v}) = \sqrt{(1 - 0)^2 + (3 - 7)^2 + (-2 - 2)^2 + (7 - 2)^2} = \sqrt{58}$$

## Dot Product

**DEFINITION** If  $\mathbf{u} = (u_1, u_2, \dots, u_n)$  and  $\mathbf{v} = (v_1, v_2, \dots, v_n)$  are vectors in  $\mathbb{R}^n$ , then the *dot product* (also called the *Euclidean inner product*) of  $\mathbf{u}$  and  $\mathbf{v}$  is denoted by  $\mathbf{u} \cdot \mathbf{v}$  and is defined by

$$\mathbf{u} \cdot \mathbf{v} = u_1v_1 + u_2v_2 + \dots + u_nv_n$$

We define the **angle between  $\mathbf{u}$  and  $\mathbf{v}$**  to be the angle  $\theta$  determined by  $\mathbf{u}$  and  $\mathbf{v}$  that satisfies the inequalities  $0 \leq \theta \leq \pi$



**DEFINITION** If  $\mathbf{u}$  and  $\mathbf{v}$  are nonzero vectors in  $R^2$  or  $R^3$ , and if  $\theta$  is the angle between  $\mathbf{u}$  and  $\mathbf{v}$ , then the *dot product* (also called the *Euclidean inner product*) of  $\mathbf{u}$  and  $\mathbf{v}$  is denoted by  $\mathbf{u} \cdot \mathbf{v}$  and is defined as

$$\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos \theta$$

If  $\mathbf{u} = \mathbf{0}$  or  $\mathbf{v} = \mathbf{0}$ , then we define  $\mathbf{u} \cdot \mathbf{v}$  to be 0.

The notion of “angle” between nonzero vectors  $\mathbf{u}$  and  $\mathbf{v}$  is given below

$$\theta = \cos^{-1} \left( \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \|\mathbf{v}\|} \right)$$

# Algebraic Properties

$$\mathbf{v} \cdot \mathbf{v} = v_1^2 + v_2^2 + \cdots + v_n^2 = \|\mathbf{v}\|^2$$

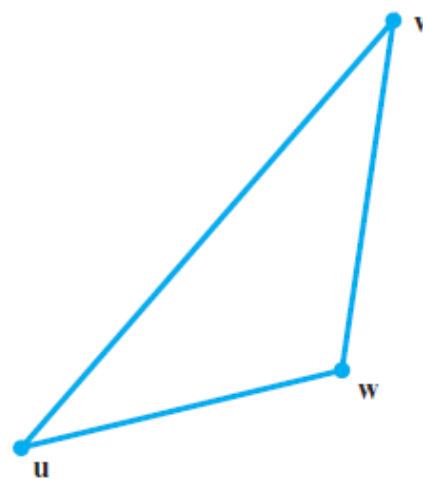
This yields the following formula for expressing the length of a vector in terms of a dot product:

$$\|\mathbf{v}\| = \sqrt{\mathbf{v} \cdot \mathbf{v}}$$

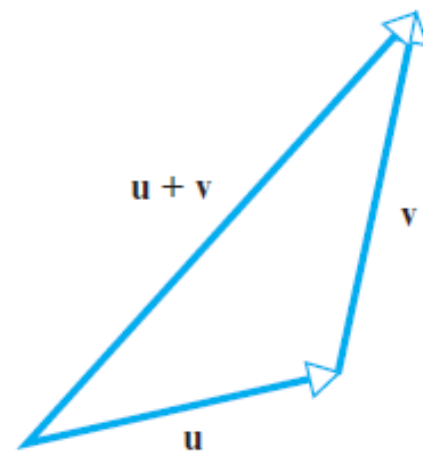
**THEOREM** If  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  are vectors in  $R^n$ , then:

(a)  $\|\mathbf{u} + \mathbf{v}\| \leq \|\mathbf{u}\| + \|\mathbf{v}\|$  [Triangle inequality for vectors]

(b)  $d(\mathbf{u}, \mathbf{v}) \leq d(\mathbf{u}, \mathbf{w}) + d(\mathbf{w}, \mathbf{v})$  [Triangle inequality for distances]



$$d(\mathbf{u}, \mathbf{v}) \leq d(\mathbf{u}, \mathbf{w}) + d(\mathbf{w}, \mathbf{v})$$



$$\|\mathbf{u} + \mathbf{v}\| \leq \|\mathbf{u}\| + \|\mathbf{v}\|$$

**DEFINITION** Two nonzero vectors  $\mathbf{u}$  and  $\mathbf{v}$  in  $R^n$  are said to be *orthogonal* (or *perpendicular*) if  $\mathbf{u} \cdot \mathbf{v} = 0$ .

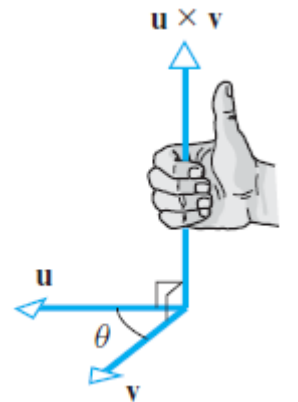
**Examples:**

- (a) Show that  $\mathbf{u} = (-2, 3, 1, 4)$  and  $\mathbf{v} = (1, 2, 0, -1)$  are orthogonal vectors in  $R^4$ .
- (b) Let  $S = \{\mathbf{i}, \mathbf{j}, \mathbf{k}\}$  be the set of standard unit vectors in  $R^3$ . Show that each ordered pair of vectors in  $S$  is orthogonal.

# Cross Product

**DEFINITION** If  $\mathbf{u} = (u_1, u_2, u_3)$  and  $\mathbf{v} = (v_1, v_2, v_3)$  are vectors in 3-space, then the *cross product*  $\mathbf{u} \times \mathbf{v}$  is the vector defined by

$$\begin{aligned}\mathbf{u} \times \mathbf{v} &= \left( \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix}, - \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix}, \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} \right) \\ &= (u_2v_3 - u_3v_2, u_3v_1 - u_1v_3, u_1v_2 - u_2v_1)\end{aligned}$$



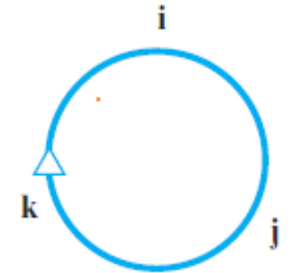
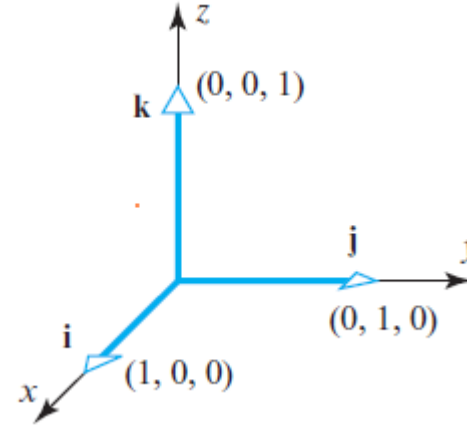
## Example: Cross Products of the Standard Unit Vectors

Show the following results

$$\mathbf{i} \times \mathbf{i} = \mathbf{0} \quad \mathbf{j} \times \mathbf{j} = \mathbf{0} \quad \mathbf{k} \times \mathbf{k} = \mathbf{0}$$

$$\mathbf{i} \times \mathbf{j} = \mathbf{k} \quad \mathbf{j} \times \mathbf{k} = \mathbf{i} \quad \mathbf{k} \times \mathbf{i} = \mathbf{j}$$

$$\mathbf{j} \times \mathbf{i} = -\mathbf{k} \quad \mathbf{k} \times \mathbf{j} = -\mathbf{i} \quad \mathbf{i} \times \mathbf{k} = -\mathbf{j}$$



$$\mathbf{i} \times \mathbf{j} = \left( \begin{vmatrix} 0 & 0 \\ 1 & 0 \end{vmatrix}, - \begin{vmatrix} 1 & 0 \\ 0 & 0 \end{vmatrix}, \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} \right) = (0, 0, 1) = \mathbf{k}$$

## Scalar triple product

The scalar triple product of  $\mathbf{u} = (u_1, u_2, u_3)$ ,  $\mathbf{v} = (v_1, v_2, v_3)$ , and  $\mathbf{w} = (w_1, w_2, w_3)$  can be calculated from the formula

$$\mathbf{u} \cdot (\mathbf{v} \times \mathbf{w}) = \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

**Example:** Calculate the scalar triple product  $\mathbf{u} \cdot (\mathbf{v} \times \mathbf{w})$  of the vectors

$$\mathbf{u} = 3\mathbf{i} - 2\mathbf{j} - 5\mathbf{k}, \quad \mathbf{v} = \mathbf{i} + 4\mathbf{j} - 4\mathbf{k}, \quad \mathbf{w} = 3\mathbf{j} + 2\mathbf{k}$$

*Solution*

$$\begin{aligned} \mathbf{u} \cdot (\mathbf{v} \times \mathbf{w}) &= \begin{vmatrix} 3 & -2 & -5 \\ 1 & 4 & -4 \\ 0 & 3 & 2 \end{vmatrix} \\ &= 3 \begin{vmatrix} 4 & -4 \\ 3 & 2 \end{vmatrix} - (-2) \begin{vmatrix} 1 & -4 \\ 0 & 2 \end{vmatrix} + (-5) \begin{vmatrix} 1 & 4 \\ 0 & 3 \end{vmatrix} \\ &= 60 + 4 - 15 = 49 \end{aligned}$$

**Exercises:** Let  $\mathbf{u} = (3, 2, -1)$ ,  $\mathbf{v} = (0, 2, -3)$ , and  $\mathbf{w} = (2, 6, 7)$ .

Compute the indicated vectors

- (a)  $\mathbf{v} \times \mathbf{w}$                       (b)  $\mathbf{w} \times \mathbf{v}$                       (c)  $(\mathbf{u} + \mathbf{v}) \times \mathbf{w}$   
(d)  $\mathbf{v} \cdot (\mathbf{v} \times \mathbf{w})$                 (e)  $\mathbf{v} \times \mathbf{v}$                       (f)  $(\mathbf{u} - 3\mathbf{w}) \times (\mathbf{u} - 3\mathbf{w})$
- (a)  $\mathbf{u} \times \mathbf{v}$                       (b)  $-(\mathbf{u} \times \mathbf{v})$                       (c)  $\mathbf{u} \times (\mathbf{v} + \mathbf{w})$   
(d)  $\mathbf{w} \cdot (\mathbf{w} \times \mathbf{v})$                 (e)  $\mathbf{w} \times \mathbf{w}$                       (f)  $(7\mathbf{v} - 3\mathbf{u}) \times (7\mathbf{v} - 3\mathbf{u})$

## Exercises

Compute the scalar triple product  $\mathbf{u} \cdot (\mathbf{v} \times \mathbf{w})$

1.  $\mathbf{u} = (-2, 0, 6)$ ,  $\mathbf{v} = (1, -3, 1)$ ,  $\mathbf{w} = (-5, -1, 1)$

2.  $\mathbf{u} = (-1, 2, 4)$ ,  $\mathbf{v} = (3, 4, -2)$ ,  $\mathbf{w} = (-1, 2, 5)$

3.  $\mathbf{u} = (a, 0, 0)$ ,  $\mathbf{v} = (0, b, 0)$ ,  $\mathbf{w} = (0, 0, c)$

4.  $\mathbf{u} = \mathbf{i}$ ,  $\mathbf{v} = \mathbf{j}$ ,  $\mathbf{w} = \mathbf{k}$